

## Liverpool John Moores University

Title: CONTROL SYSTEMS  
Status: Definitive  
Code: **6500TECCBT** (118464)  
Version Start Date: 01-08-2016

Owning School/Faculty: Electronics and Electrical Engineering  
Teaching School/Faculty: Partner College

Team	Leader
Dingli Yu	Y

**Academic Level:** FHEQ6  
**Credit Value:** 12  
**Total Delivered Hours:** 37  
**Total Learning Hours:** 120  
**Private Study:** 83

### Delivery Options

Course typically offered: Semester 2

Component	Contact Hours
Lecture	20
Practical	5
Tutorial	10

**Grading Basis:** 40 %

### Assessment Details

Category	Short Description	Description	Weighting (%)	Exam Duration
Exam	AS1	Examination	70	2
Report	AS2	Coursework	30	

### Aims

*To extend the basic concepts of control in level 2 in the design and analysis of control systems.*

### Learning Outcomes

After completing the module the student should be able to:

- 1 analyse and design dynamic compensation employing frequency analysis
- 2 construct root locus of closed-loop system response and design systems using root locus technique
- 3 examine and evaluate system stability
- 4 understand the state space concept and characteristics of linear systems
- 5 apply state feedback control with pole-placement method
- 6 design and simulate control systems using computer software, e.g. Matlab/Simulink

### Learning Outcomes of Assessments

The assessment item list is assessed via the learning outcomes listed:

EXAM	1	2	3	4	5
CW	1	2	6		

### Outline Syllabus

*Root locus: root locus concepts and construction. Analysis and design with root locus. Frequency analysis: Nyquist criterion, Bode plots, design criteria in frequency domain. Compensation of systems with frequency analysis method.*  
*State space: state variables and state space models, stability, controllability and observability, state feedback control by pole placement*

### Learning Activities

Combination of lectures, tutorials and laboratory work

### Notes

This level 3 module extends level 2 concepts into continuous control design using frequency response, root locus and state space methods.