

Liverpool John Moores University

Title: CONTROL SYSTEMS
Status: Definitive
Code: **6525ENGIOM** (117275)
Version Start Date: 01-08-2016

Owning School/Faculty: Maritime and Mechanical Engineering
Teaching School/Faculty: Maritime and Mechanical Engineering

| Team | Leader |
|-----------------|--------|
| Russell English | Y |
| Barry Gomm | |

Academic Level: FHEQ6 **Credit Value:** 20 **Total Delivered Hours:** 50
Total Learning Hours: 200 **Private Study:** 150

Delivery Options

Course typically offered: Standard Year Long

| Component | Contact Hours |
|-----------|---------------|
| Lecture | 36 |
| Practical | 12 |

Grading Basis: 40 %

Assessment Details

| Category | Short Description | Description | Weighting (%) | Exam Duration |
|----------|-------------------|-------------|---------------|---------------|
| Exam | Exam | | 50 | 2 |
| Essay | Essay | | 25 | |
| Essay | Essay | | 25 | |

Aims

To extend the basic concepts of control in level 5 in the design and analysis of continuous and digital control systems

Learning Outcomes

After completing the module the student should be able to:

- 1 Analyse and design control systems employing frequency analysis
- 2 Construct root locus of closed-loop systems and design systems using root locus technique
- 3 Apply the state space concept to analyse linear systems and design state feedback control with pole-placement method
- 4 Analyse and synthesize sampled-data systems in the z-domain
- 5 Design and simulate control systems using computer software, e.g. Matlab/Simulink, Scilab

Learning Outcomes of Assessments

The assessment item list is assessed via the learning outcomes listed:

| | | | | |
|---------|---|---|---|---|
| Exam | 1 | 2 | 3 | 4 |
| Essay 1 | 1 | 5 | | |
| Essay 2 | 2 | 4 | 5 | |

Outline Syllabus

Root locus: root locus concepts and construction. analysis and design with root locus. Frequency analysis: Nyquist criterion, Bode plots, design criteria in frequency domain.

State space: state variables and state space models, controllability and observability, pole placement by state feedback, state observers.

Digital systems: sampled-data systems, pulse transfer function, closed-loop transfer function, stability analysis, implementation of digital controllers, discrete system simulation

Learning Activities

Combination of lectures and laboratory work

Notes

This level 6 module extends level 5 concepts into continuous control design using frequency response, root locus and state space methods. It also extends level 5 concepts into discrete control system modelling and controller design by mathematical analysis and synthesis.